

METROPOLIS ALGORITHM: AN EXAMPLE ①

Let $\pi(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$ on \mathbb{R}

STATE SPACE: continuous variable in \mathbb{R}

DYNAMICS: At time t the system is in x : $x_t = x$

We must define x_{t+1} , the position at time $t+1$.

We fix p (parameter that defines $P^{(0)}$) [IT CAN BE OPTIMIZED]

STEP 1 (PROPOSAL): We choose y uniformly in the interval $[x-p, x+p]$

STEP 2 (ACCEPTANCE): We accept y with probability A_{xy}

We now verify that $P_{xy}^{(0)}$ is SYMMETRIC

Choose two points x and y and ϵ small (infinitesimal)

If $|x-y| > p \Rightarrow P_{xy}^{(0)} = P_{yx}^{(0)} = 0$

Correction: replace epsilon with epsilon/(2p)

If $|x-y| < p \Rightarrow \left\{ \begin{array}{l} \text{Prob}(x \rightarrow [y, y+\epsilon]) = \epsilon \\ \text{Prob}(y \rightarrow [x, x+\epsilon]) = \epsilon \end{array} \right\} \text{ (EQUALLY)}$

For a symmetric $P_{xy}^{(0)}$ we have

$$R_{xy} = \frac{\pi_y P_{yx}^{(0)}}{\pi_x P_{xy}^{(0)}} = \frac{\pi_y}{\pi_x} = e^{x^2 - y^2}$$

It follows

$$A_{xy} = \min(1, e^{x^2 - y^2})$$

IMPLEMENTATION OF ONE ITERATION

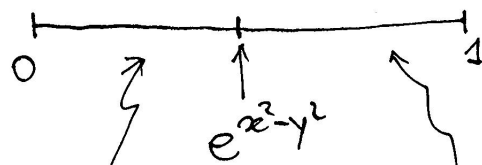
SET $X = X_{i-1}$ $Y = X + 2p(\text{RAN}() - 0.5)$ (PROPOSAL)if $(y < x)$ $x_i = y$

else if $(e^{x^2 - y^2} < \text{RAN}())$	$x_i = x$	(REJECTED)
else	$x_i = y$	(ACCEPTED)

COMMENTS

- $2p(\text{RAN}() - 0.5)$ gives a random number uniformly distributed in $[-p, p]$
- if $y \leq x$, $e^{x^2 - y^2} > 1$ so that $A_{xy} = 1$ the move is accepted
- if $y > x$, $e^{x^2 - y^2} < 1$ so that $A_{xy} = e^{x^2 - y^2}$
In this case we should accept y with probability $e^{x^2 - y^2}$

The strategy is the following



If $\text{RAN}()$ falls here, y is accepted

If $\text{RAN}()$ falls here, y is rejected

ANOTHER ALGORITHM (useful for simulated tempering / parallel tempering)

③

STATE SPACE: 5 discrete points

PROBABILITY: $\pi_x = \{ \pi_1, \pi_2, \pi_3, \pi_4, \pi_5 \}$

DYNAMICS:

STEP 1: (proposal)

$$\begin{cases} \text{if } x=2,3,4 & \text{we propose } \begin{cases} y=x+1 & \text{prob. } 1/2 \\ y=x-1 & \text{prob } 1/2 \end{cases} \\ \text{if } x=1 & \text{we propose } y=2 \text{ with prob } 1 \\ \text{if } x=5 & \text{we propose } y=4 \text{ with prob } 1 \end{cases}$$

STEP 2: (acceptance) we accept y with prob A_{xy} .

In this case $P_{xy}^{(0)}$ is not symmetric

The proposal can be implemented as follows

if $(x=1)$ $y=2$ $[x=x_{t-1}]$
$$R = \frac{P_{21}^{(0)} \pi_2}{P_{12}^{(0)} \pi_1} = \frac{\pi_2}{2\pi_1}$$

if $(x=2)$ if $(\text{RAN}() < 0.5)$ $y=1$
$$R = \frac{P_{12}^{(0)} \pi_1}{P_{21}^{(0)} \pi_2} = \frac{2\pi_1}{\pi_2}$$

else

$y=3$
$$R = \frac{P_{32}^{(0)} \pi_3}{P_{23}^{(0)} \pi_2} = \frac{\pi_3}{\pi_2}$$

if $(x > 2 \ \&\& \ x < 4)$ if $(\text{RAN}() < 0.5)$ $y = x + 1$ ④
 else $y = x - 1$

$$R = \frac{\pi_y}{\pi_x}$$

if $(x = 4)$ if $(\text{RAN}() < 0.5)$ $y = 3$
 $R = \frac{P_{34}^{(0)} \pi_3}{P_{43}^{(0)} \pi_4} = \frac{\pi_3}{\pi_4}$

else

$$y = 5$$

$$R = \frac{P_{54}^{(0)} \pi_5}{P_{45}^{(0)} \pi_4} = \frac{2\pi_5}{\pi_4}$$

if $(x = 5)$ $y = 4$
 $R = \frac{P_{45}^{(0)} \pi_4}{P_{54}^{(0)} \pi_5} = \frac{\pi_4}{2\pi_5}$

The move is accepted with probability $\min(1, R)$ and can be implemented as follows

if $(R \geq 1)$ $x_i = y$

else if $(\text{RAN}() < R)$ $x_i = y$

else $x_i = x_{i-1}$ (rejection)

EXERCISE :

(5)

We can also define a symmetric proposal :

$$\text{if } x=2,3,4 \text{ we propose } \begin{cases} y=x+1 & \text{prob } 1/2 \\ y=x-1 & \text{prob } 1/2 \end{cases}$$

$$\text{if } x=1 \text{ we propose } \begin{cases} y=2 & \text{prob } 1/2 \\ y=1 & \text{prob } 1/2 \end{cases}$$

$$\text{if } x=5 \text{ we propose } \begin{cases} y=5 & \text{prob } 1/2 \\ y=4 & \text{prob } 1/2 \end{cases}$$

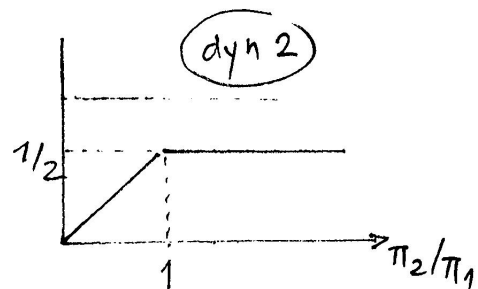
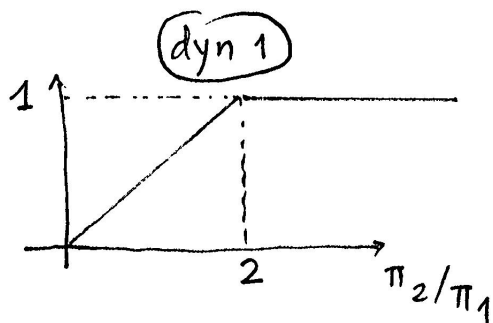
As an exercise show that $P_{xy}^{(0)} = P_{yx}^{(0)}$ for all (x,y) .

QUESTION: is this dynamics more efficient or less efficient than the first one?

There is a difference only at the boundaries
Let's compute P_{12} for the two dynamics

$$\begin{aligned} \text{dynamic 1: } P_{12} &= P_{12}^{(0)} A_{12} = 1 \times \min\left(1, \frac{\pi_2}{2\pi_1}\right) \\ &= \min\left(1, \frac{\pi_2}{2\pi_1}\right) \end{aligned}$$

$$\begin{aligned} \text{dynamic 2: } P_{12} &= P_{12}^{(0)} A_{12} = \\ &= \frac{1}{2} \min\left(1, \frac{\pi_2}{\pi_1}\right) \end{aligned}$$



DYN 1 is MORE efficient