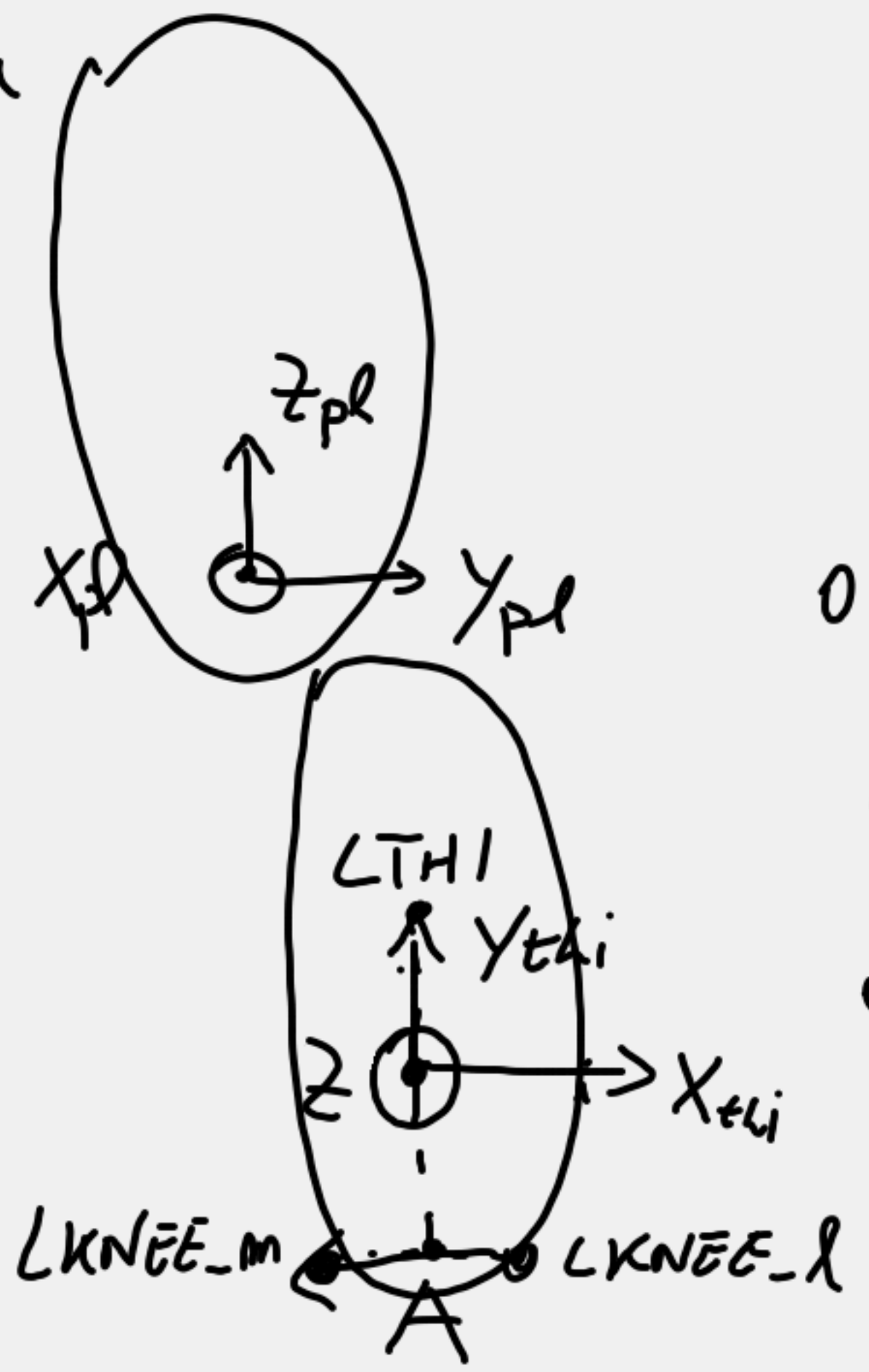


1.a



$${}^0A = \frac{{}^0LKNEE_m + {}^0LKNEE_l}{2}$$

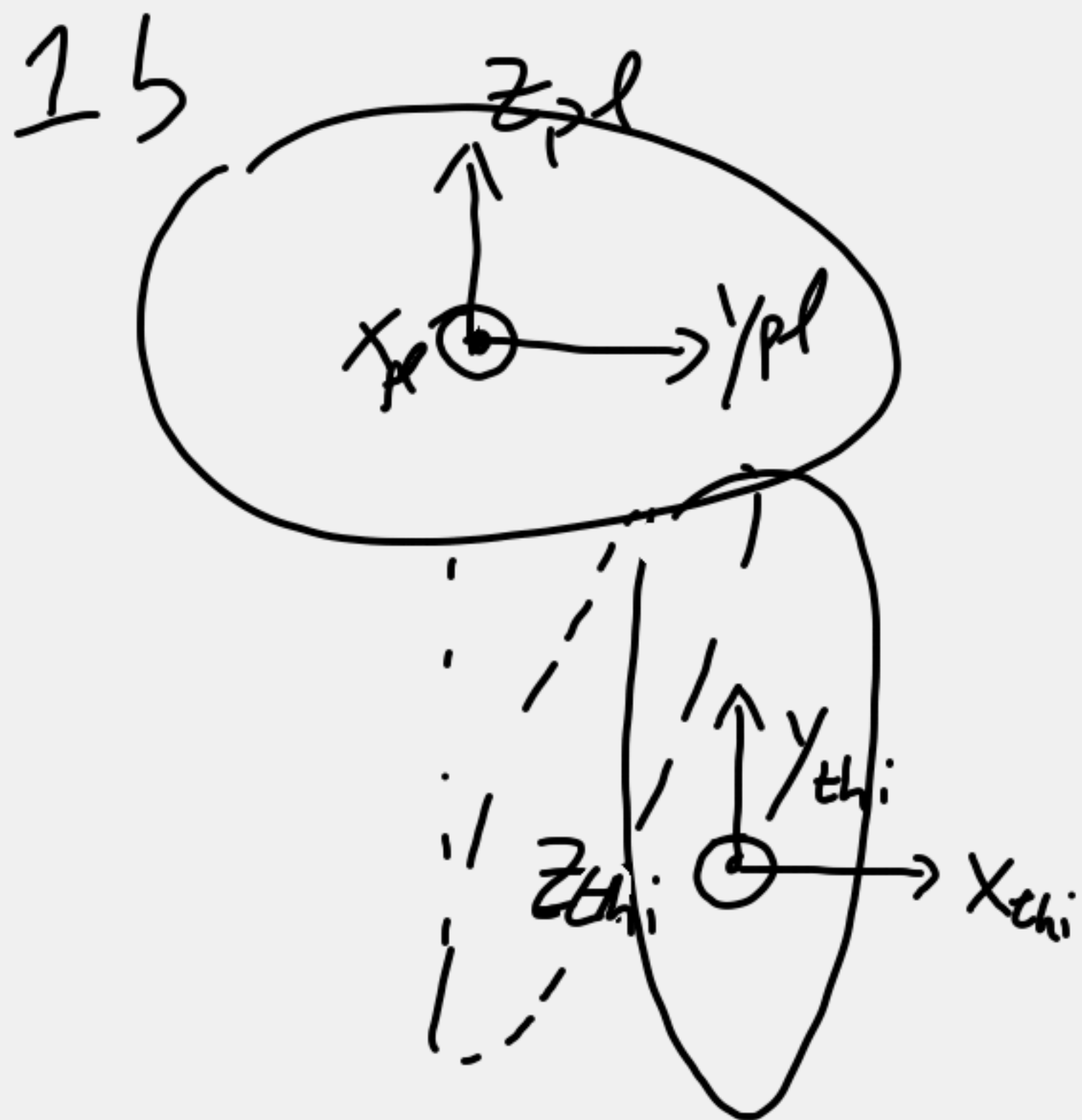
$${}^0O_{thi} = \frac{{}^0LTHI + {}^0A}{2}$$

$${}^0y_{thi} = \text{VERS}({}^0LTHI - {}^0O_{thi})$$

$${}^0z_{thi} = \text{VERS}({}^0y_{thi} \times (LKNEE_m - LKNEE_l))$$

$${}^0x_{thi} = {}^0y_{thi} \times {}^0z_{thi}$$

$${}^0 T_{thi} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

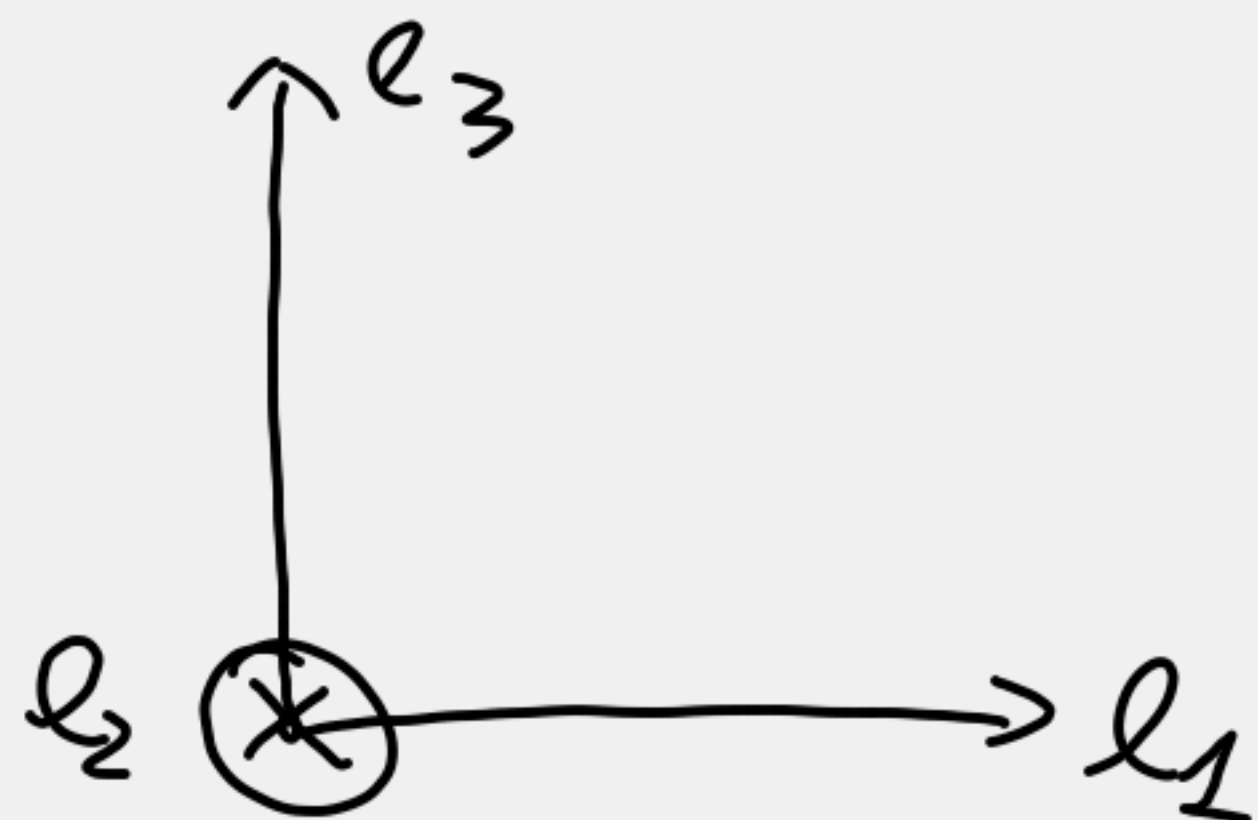


$l_1: \bar{F}l/\bar{E}x$
 $l_2: A_{b01}/A_{o1}$
 $l_3: W/Ext ROT$

$l_1 \parallel y_{pl}$

$l_3 \parallel y_{thi}$

$l_2 \perp l_1, l_3$



$y \ x' \ y''; y \ z' \ y''$

$l_1: \bar{E}ST. \oplus$

$l_2: ADD \oplus$

$l_3: EX ROT \oplus$

$$1c \quad y \quad z' \quad y'' \rightarrow \varphi, \theta, \psi$$

$$H(\alpha) \quad \overset{pr}{W}_{\epsilon hi}^{pr} = H(\alpha) \dot{\alpha}$$

$$W = W_{\varphi} + W_{\theta} + W_{\psi}$$

$$W_{\varphi} = \begin{bmatrix} 0 \\ \dot{\varphi} \\ 0 \end{bmatrix} ; \quad W_{\theta} = R_y(\varphi) \begin{bmatrix} 0 \\ \dot{\theta} \\ 0 \end{bmatrix}$$

$$W_{\psi} = R_y(\varphi) R_z(\theta) \begin{bmatrix} 0 \\ \dot{\psi} \\ 0 \end{bmatrix}$$

$$W_{\theta} = \begin{bmatrix} c_{\varphi} & 0 & s_{\varphi} \\ 0 & 1 & 0 \\ -s_{\varphi} & 0 & c_{\varphi} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \dot{\theta} \end{bmatrix} = \begin{bmatrix} s_{\varphi} \dot{\theta} \\ 0 \\ c_{\varphi} \dot{\theta} \end{bmatrix}$$

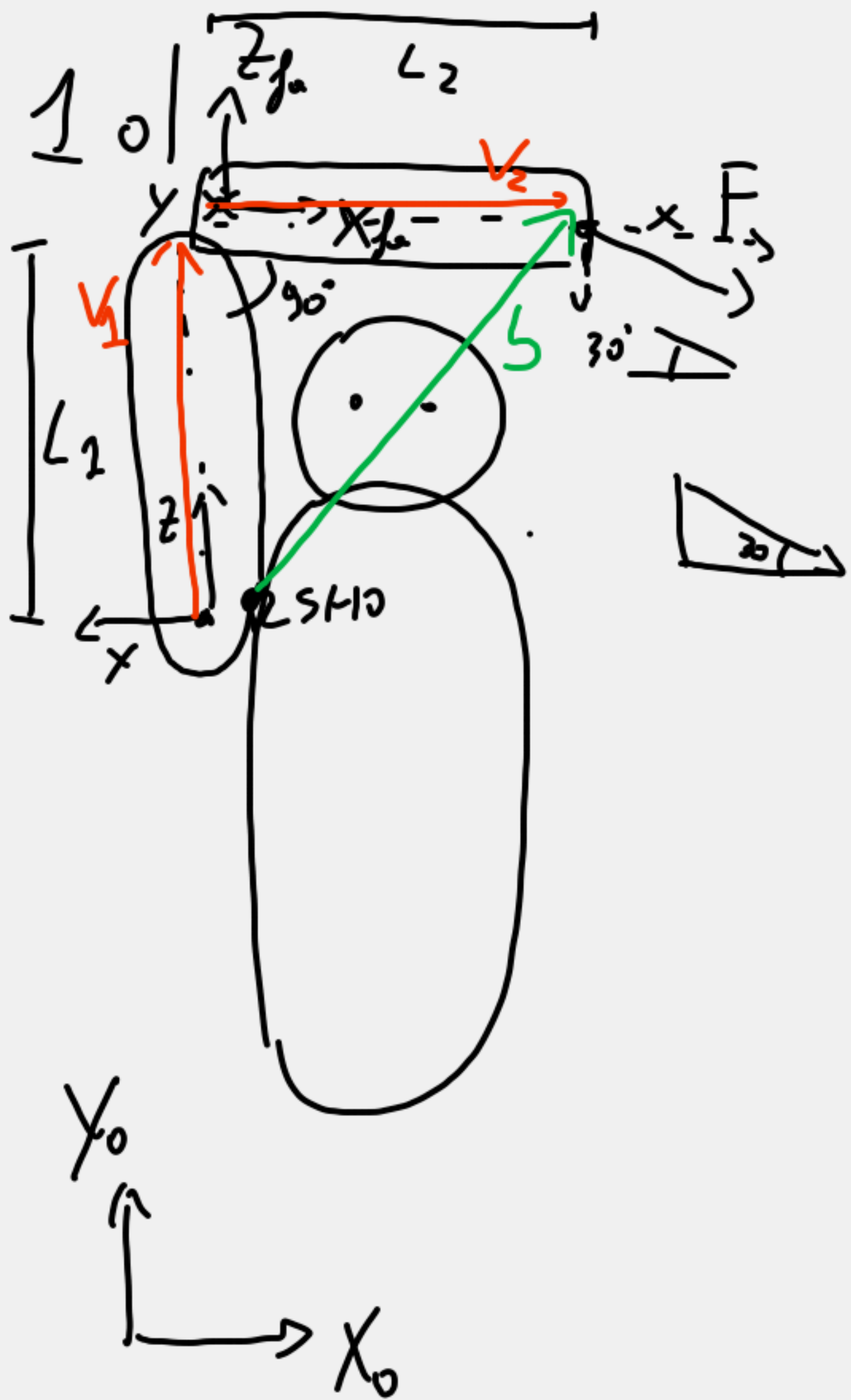
$$W_{\psi} = \begin{bmatrix} c_{\varphi} & 0 & s_{\varphi} \\ 0 & 1 & 0 \\ -s_{\varphi} & 0 & c_{\varphi} \end{bmatrix} \begin{bmatrix} c_{\theta} & -s_{\theta} & 0 \\ s_{\theta} & c_{\theta} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ \dot{\psi} \\ 0 \end{bmatrix}$$

$$W_{\psi} = \begin{bmatrix} c_{\varphi} & 0 & s_{\varphi} \\ 0 & 1 & 0 \\ -s_{\varphi} & 0 & c_{\varphi} \end{bmatrix} \begin{bmatrix} -s_{\theta} \dot{\psi} \\ c_{\theta} \dot{\psi} \\ 0 \end{bmatrix} = \begin{bmatrix} -c_{\varphi} s_{\theta} \dot{\psi} \\ c_{\theta} \dot{\psi} \\ s_{\varphi} s_{\theta} \dot{\psi} \end{bmatrix}$$

$$\omega = \begin{bmatrix} 0 \\ \dot{\psi} \\ 0 \end{bmatrix} + \begin{bmatrix} s_{\psi} \dot{\theta} \\ 0 \\ c_{\psi} \dot{\theta} \end{bmatrix} + \begin{bmatrix} -c_{\psi} s_{\theta} \dot{\psi} \\ c_{\theta} \dot{\psi} \\ s_{\psi} s_{\theta} \dot{\psi} \end{bmatrix} = \begin{bmatrix} s_{\psi} \dot{\theta} - c_{\psi} s_{\theta} \dot{\psi} \\ \dot{\psi} + c_{\theta} \dot{\psi} \\ c_{\psi} \dot{\theta} + s_{\psi} s_{\theta} \dot{\psi} \end{bmatrix}$$

$$\omega = H \begin{bmatrix} \dot{\psi} \\ \dot{\theta} \\ \dot{\psi} \end{bmatrix}$$

$$H = \begin{bmatrix} 0 & s_{\psi} & -c_{\psi} s_{\theta} \\ 1 & 0 & c_{\theta} \\ 0 & c_{\psi} & s_{\psi} s_{\theta} \end{bmatrix} \begin{bmatrix} \dot{\psi} \\ \dot{\theta} \\ \dot{\psi} \end{bmatrix} = \begin{bmatrix} s_{\psi} \dot{\theta} - c_{\psi} s_{\theta} \dot{\psi} \\ \dot{\psi} + c_{\theta} \dot{\psi} \\ c_{\psi} \dot{\theta} + s_{\psi} s_{\theta} \dot{\psi} \end{bmatrix}$$



$$\text{form } \vec{m} = ?$$

$$\vec{b} = \vec{v}_1 + \vec{v}_2$$

$$\vec{m} = \vec{b} \times \vec{F}$$

$$\text{form } \vec{v}_2 = \begin{bmatrix} 250 \\ 0 \\ 0 \end{bmatrix} \text{ mm}$$

$$\text{form } \vec{m} = \vec{b} \times \vec{F}$$

$$\text{form } \vec{v}_1 = \begin{bmatrix} 0 \\ 0 \\ 270 \end{bmatrix} \text{ mm}$$

$$\text{form } \vec{F} = \begin{bmatrix} \frac{\sqrt{3}}{2} \\ 0 \\ 1 \end{bmatrix} \cdot 50 \text{ N}$$

$$\text{form } \vec{b} = \begin{bmatrix} 0 \\ 0 \\ 270 \end{bmatrix} + \begin{bmatrix} 250 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 250 \\ 0 \\ 270 \end{bmatrix} \text{ mm}$$

$$\underline{\underline{f_{arm} V_1}} = \underline{\underline{R_{arm} V_1}}$$

$$R_2(180) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{arm} = \begin{pmatrix} f_{arm} & | & f_{arm} & | & f_{arm} \\ X_{arm} & & Y_{arm} & & Z_{arm} \\ | & & | & & | \\ -1 & & 0 & & 0 \\ 0 & & -1 & & 0 \\ 0 & & 0 & & 1 \end{pmatrix}$$

$$R_2(180) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$b = \begin{bmatrix} 0,25 \\ 0 \\ 0,27 \end{bmatrix} m$$

$$\begin{vmatrix} i & j & k & i & j \\ 0,25 & 1 & 0 & 0,25 & 0 \\ \frac{\sqrt{3}}{2} 50 & 1 & 0 & \frac{\sqrt{3}}{2} 50 & 0 \\ 0 & 1 & -\frac{50}{2} & 0 & 1 \end{vmatrix} =$$

$$= J \left(0,27 \cdot \frac{\sqrt{3}}{2} 50 \right) - J \left(0,25 \cdot -\frac{50}{2} \right) = J 17,94 \text{ Nm}$$

$$f_{\text{arm } m} = \begin{bmatrix} 0 \\ 17,94 \\ 0 \end{bmatrix} \text{ Nm}$$